

Electronic Companion

Resource Allocation under Demand Uncertainty and Private Information

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Appendix EC.1: Proofs in Section 3

Proof of Theorem 1 and Proposition 1. We divide the proof in two steps: i) the main arguments, and ii) proof of Proposition 1 and finer properties of q° used in i).

Step 1. Main Arguments. Consider the following relaxed *ex ante* problem

$$\min_{q,m} \mathbb{E}_{x,y} \left[C_0 \left(x, \sum_{i=1}^M q_i(x,y) \right) + \sum_{i=1}^M m_i(x,y) \right] \quad \text{subject to } (\mathbf{IR}_i^P) \text{ and } 0 \leq q_i(x,y) \leq y_i, \quad i = 1, \dots, M.$$

It is obvious that all the constraints in (\mathbf{IR}_i^P) necessarily bind and hence we can impose them as equalities to eliminate the variable m from the above problem, rendering the objective function to

$$\mathbb{E}_{x,y} \left[C_0 \left(x, \sum_{i=1}^M q_i(x,y) \right) + \sum_{i=1}^M C_i(y_i, q_i(x,y)) - \sum_{i=1}^M C_i(y_i, 0) \right],$$

which coincides with the objective function of the first-best problem (4) and is minimized by q° .

In particular, setting $m_i^\circ(x,y) = (c_i - h_i) q_i^\circ(x,y)$ implies that (\mathbf{IR}_i^P) holds with equality *ex post* for all $i = 1, \dots, M$.

Therefore, it remains to show that the policy $\{q_i^\circ(x,y), m_i^\circ(x,y)\}_{i=1}^M$ also satisfies (\mathbf{IC}_i^P) *ex post*, (\mathbf{IC}_0^P) and (\mathbf{IR}_0^P) . For any x, y , we have

$$C_i(y_i, q_i^\circ(x,y)) - m_i^\circ(x,y) = C_i(y_i, 0) = h_i y_i, \quad \text{for } i = 1, \dots, M,$$

which implies that (\mathbf{IC}_i^P) holds with equality *ex post*. Moreover, by (4) we have

$$C_0 \left(x, \sum_{i=1}^M q_i^\circ(x,y) \right) + \sum_{i=1}^M C_i(y_i, q_i^\circ(x,y)) \leq C_0(x, 0) + \sum_{i=1}^M C_i(y_i, 0)$$

and by the previous equality

$$\begin{aligned} C_0 \left(x, \sum_{i=1}^M q_i^\circ(x,y) \right) + \sum_{i=1}^M m_i^\circ(x,y) &= C_0 \left(x, \sum_{i=1}^M q_i^\circ(x,y) \right) + \sum_{i=1}^M [C_i(y_i, q_i^\circ(x,y)) - C_i(y_i, 0)] \\ &\leq C_0(x, 0). \end{aligned}$$

The last inequality is (\mathbf{IR}_0^P) . Finally, to see that (\mathbf{IC}_0^P) also holds, for each x, x', y , define

$$\begin{aligned} \Delta(x, x', y) &:= C_0 \left(x, \sum_{i=1}^M q_i^\circ(x,y) \right) + \sum_{i=1}^M m_i^\circ(x,y) - \left[C_0 \left(x, \sum_{i=1}^M q_i^\circ(x',y) \right) + \sum_{i=1}^M m_i^\circ(x',y) \right] \\ &= (h_0 + p_0) \int_{-x + \sum_{i=1}^N q_i^\circ(x',y)}^{-x + \sum_{i=1}^N q_i^\circ(x,y)} G_0(z) dz - \sum_{i=1}^M (p_0 + h_i - c_i) (q_i^\circ(x,y) - q_i^\circ(x',y)). \end{aligned}$$

We will show that $\Delta(x, x', y) \leq 0$ hence (IC_0^P) holds by integrating y out.

Let $\eta_i = G_0^{-1}((h_i + p_0 - c_i)/(h_0 + p_0))$ for $i = 1, \dots, M$. Note that η_i is decreasing in $i = 1, \dots, M$ since $c_i - h_i$ is increasing. The index $i^\circ(x, y)$ is defined in Step 2 below.

If $\eta_1 \leq -x < -x'$, then $q_i^\circ(x, y) = q_i^\circ(x', y) = 0$ by Step 2 (***) and hence $\Delta(x, x', y) = 0$.

If $-x < -x'$ and $-x \leq \eta_i \leq -x + \sum_{j=1}^M y_j$ for some $i = 1, \dots, M$, then by Step 2 (**),

$$G_0 \left(-x + \sum_{j=1}^M q_j^\circ(x, y) \right) = \frac{p_0 + h_{i^\circ(x, y)} - c_{i^\circ(x, y)}}{h_0 + p_0}.$$

Furthermore, we have $q_i^\circ(x, y) \geq q_i^\circ(x', y)$ by Step 2 (*). Hence,

$$\begin{aligned} \Delta(x, x', y) &\leq \sum_{i=1}^{i^\circ(x, y)} \left[(h_0 + p_0) G_0 \left(-x + \sum_{i=1}^N q_i^\circ(x, y) \right) - (p_0 + h_i - c_i) \right] (q_i^\circ(x, y) - q_i^\circ(x', y)) \\ &= \sum_{i=1}^{i^\circ(x, y)} \underbrace{[(h_{i^\circ(x, y)} - c_{i^\circ(x, y)}) - (h_i - c_i)]}_{\leq 0} \underbrace{(q_i^\circ(x, y) - q_i^\circ(x', y))}_{\geq 0} \leq 0. \end{aligned}$$

If $-x < -x'$ and $\eta_M \geq -x + \sum_{i=1}^M y_i$, then by Step 2 (***),

$$G_0 \left(-x + \sum_{j=1}^M q_j^\circ(x, y) \right) \leq \frac{p_0 + h_M - c_M}{h_0 + p_0}.$$

Furthermore, we have $q_i^\circ(x, y) \geq q_i^\circ(x', y)$ by Step 2 (*). Hence,

$$\begin{aligned} \Delta(x, x', y) &\leq \sum_{i=1}^M \left[(h_0 + p_0) G_0 \left(-x + \sum_{i=1}^N x_i \right) - (p_0 + h_i - c_i) \right] (q_i^\circ(x, y) - q_i^\circ(x', y)) \\ &\leq \sum_{i=1}^M \underbrace{[(h_M - c_M) - (h_i - c_i)]}_{\leq 0} \underbrace{(q_i^\circ(x, y) - q_i^\circ(x', y))}_{\geq 0} \leq 0. \end{aligned}$$

If $-x > -x' \geq \eta_1$, then $q_i^\circ(x, y) = q_i^\circ(x', y) = 0$ by Step 2 (***) and hence $\Delta(x, x', y) = 0$.

If $-x > \eta_1 \geq -x'$, we have $0 = i^\circ(x, y) < i^\circ(x', y)$ and $0 = q_i^\circ(x, y) \leq q_i^\circ(x', y)$ for all $i = 1, \dots, M$ by Step 2 (***)

$$\begin{aligned} \Delta(x, x', y) &\leq \sum_{i=1}^{i^\circ(x', y)} [(h_0 + p_0) G_0(-x) - (p_0 + h_i - c_i)] (q_i^\circ(x, y) - q_i^\circ(x', y)) \\ &\leq \sum_{i=i^\circ(x, y)}^{i^\circ(x', y)} \underbrace{[(h_1 - c_1) - (h_i - c_i)]}_{\geq 0} \underbrace{(q_i^\circ(x, y) - q_i^\circ(x', y))}_{\leq 0} \leq 0. \end{aligned}$$

If $-x > -x'$, which implies $i^\circ(x, y) \leq i^\circ(x', y)$ and $q_i^\circ(x, y) \leq q_i^\circ(x', y)$ by Step 2 (*), and $-x \leq \eta_i \leq -x + \sum_{i=1}^M y_i$ for some $i = 1, \dots, M$, which implies, by Step 2 (**),

$$G_0 \left(-x + \sum_{j=1}^M q_j^\circ(x, y) \right) = \frac{p_0 + h_{i^\circ(x, y)} - c_{i^\circ(x, y)}}{h_0 + p_0},$$

then we have

$$\begin{aligned} \Delta(x, x', y) &\leq \sum_{i=i^\circ(x, y)}^{i^\circ(x', y)} \left[(h_0 + p_0)G_0 \left(-x + \sum_{i=1}^N q_i^\circ(x, y) \right) - (p_0 + h_i - c_i) \right] (q_i^\circ(x, y) - q_i^\circ(x', y)) \\ &= \sum_{i=i^\circ(x, y)}^{i^\circ(x', y)} \underbrace{[(h_{i^\circ(x, y)} - c_{i^\circ(x, y)}) - (h_i - c_i)]}_{\geq 0} \underbrace{(q_i^\circ(x, y) - q_i^\circ(x', y))}_{\leq 0} \leq 0. \end{aligned}$$

If $-x > -x'$ but $\eta_M \geq -x + \sum_{i=1}^M y_i$, we have $q_i^\circ(x, y) = q_i^\circ(x', y) = y_i$ for all $i = 1, \dots, M$. Hence, $\Delta(x, x', y) = 0$.

Step 2. Proof of Proposition 1 and properties of the allocation q° .

Recall the definition of $\eta_i = G_0^{-1}((h_i + p_0 - c_i)/(h_0 + p_0))$ for $i = 1, \dots, M$. Note that η_i is decreasing in $i = 1, \dots, M$ since $c_i - h_i$ is increasing. Because of the convexity of the objective function in (4), KKT condition is necessary and sufficient for global optimality of q° , namely there exists $\nu_i, \lambda_i \geq 0$, $i = 1, \dots, M$ such that the following (in)equalities are satisfied for $i = 1, \dots, M$:

$$\begin{aligned} (h_0 + p_0)G_0 \left(-x + \sum_{j=1}^M q_j \right) - p_0 + c_i - h_i + \nu_i - \lambda_i &= 0 \\ 0 \leq q_i \leq y_i, \quad \nu_i(y_i - q_i) = 0, \quad \lambda_i q_i &= 0 \end{aligned} \tag{EC.1}$$

Hence, for given y , we consider the following greedy algorithm:

Set $i = 0$ and $q^\circ = 0$. If $-x \geq \eta_1$, **terminate**.

Iteration Step: if $i \geq M$ **terminate**;

$i \leftarrow i + 1$;

if $-x + \sum_{j=1}^i y_j < \eta_i$, set $q_i^\circ = y_i$ and return to **Iteration Step**;

else set $q_i^\circ = \eta_i + x - \sum_{j=1}^{i-1} y_j$ and **terminate**.

Let i° denote the exiting index i and note that $q_i^\circ = 0$ for all $i > i^\circ$. Hence $q_i^\circ(x, y)$, $i = 1, \dots, M$, is the one given in (6). Moreover, define

$$\nu_i = \begin{cases} (c_{i^\circ} - h_{i^\circ}) - (c_i - h_i), & \text{if } i < i^\circ, \\ 0, & \text{if } i \geq i^\circ, \end{cases} \text{ and } \lambda_i = \begin{cases} 0, & \text{if } i \leq i^\circ, \\ (c_i - h_i) - (c_{i^\circ} - h_{i^\circ}), & \text{if } i > i^\circ. \end{cases}$$

Then $\nu_i, \lambda_i \geq 0$ for all i , together with $q_i^\circ(x, y)$, $i = 1, \dots, M$ satisfy (EC.1). Therefore, $q_i^\circ(x, y)$, $i = 1, \dots, M$, indeed solves (4).

It follows that:

(*) $i^\circ = i^\circ(x, y)$ and $q_i^\circ(x, y)$ is nondecreasing in x for $i = 1, 2, \dots, M$;

(**) $-x + \sum_{j=1}^M q_j^\circ(x, y) = \eta_{i^\circ}$ if $-x \leq \eta_i \leq -x + \sum_{i=1}^M y_i$ for some $i = 1, \dots, M$;

(***) $q_i^\circ(x, y) = 0$ for $i = 1, \dots, M$ if $-x \geq \eta_1$ (and hence $-x \geq \eta_i$ for all $i = 1, \dots, M$).

(****) $q_i^\circ(x, y) = y_i$ for $i = 1, \dots, M$ if $\eta_M \geq -x + \sum_{i=1}^M y_i$ (and hence $\eta_i \geq -x + \sum_{i=1}^M y_i$ for all $i = 1, \dots, M$). \square

Appendix EC.2: Characterization of (IC_i^D) and (IR_i^D)

Most of the derivation of this section will be based on the following straightforward calculation:

$$C_i(x_i, q_i) = (h_i + p_i) \int_{\underline{d}_i}^{q_i - x_i} G_i(z) dz + p_i(x_i - q_i), \quad i = 1, \dots, N, \quad (\text{EC.1})$$

where we recall that \underline{d}_i is the lower bound of the support of D_i . Therefore, it is straightforward to see that

$$C_i(x_i, 0) = p_i x_i, \quad i = 1, \dots, N. \quad (\text{EC.2})$$

In this section, we drop the dependence on y and abbreviate $m(x, y)$ as $m(x)$, $q(x, y)$ as $q(x)$.

Proof of Lemma 1. For any q and m , define

$$\widehat{W}_i(x_i, x'_i) := \mathbb{E}_{x_{-i}} [C_i(x_i, q_i(x'_i, x_{-i})) + m_i(x'_i, x_{-i})], \quad i = 1, \dots, N.$$

Then (IC_i^D) can be formulated as

$$W_i(x) = \min_{x'_i \in [\underline{x}_i, \bar{x}_i]} \widehat{W}_i(x_i, x'_i).$$

We have

$$\frac{\partial}{\partial x_i} \widehat{W}_i(x_i, x'_i) = \mathbb{E}_{x_{-i}} \left[\frac{\partial}{\partial x_i} C_i(x_i, q_i(x'_i, x_{-i})) \right] = \mathbb{E}_{x_{-i}} [-(h_i + p_i) G_i(q_i(x'_i, x_{-i}) - x_i) + p_i],$$

because the differentiation and expectation operators commute (Rosenthal 2000, Proposition 9.2.1).

Thus $\left| \frac{\partial}{\partial x_i} \widehat{W}_i(x_i, x'_i) \right| \leq \max\{h_i, p_i\}$ for any (x_i, x'_i) , and (A1) follows from the *envelope theorem* of Milgrom and Segal (2002). The equality in (A2) follows from the definition of $W_i(\cdot)$.

By (EC.2), we have

$$W_i(x_i) - C_i(x_i, 0) = W_i(\underline{x}_i) - C_i(\underline{x}_i, 0) - (h_i + p_i) \mathbb{E}_{x_{-i}} \left[\int_{\underline{x}_i}^{x_i} G_i(q_i(z, x_{-i}) - z) dz \right] \leq W_i(\bar{x}_i) - C_i(\bar{x}_i, 0).$$

Thus it suffices to impose only $W_i(\underline{x}_i) \leq C_i(\underline{x}_i, 0)$ to obtain the (IR_i^D) constraint, $W_i(x) - C_i(x_i, 0) \leq 0$ for all x_i . \square

Proof of Lemma 2. Notice that

$$C_i(x_i, q_i) - C_i(x'_i, q_i) = -(h_i + p_i) \int_{x'_i}^{x_i} G_i(q_i - z) dz + p_i(x_i - x'_i).$$

Combining this equation and (EC.2), we have

$$\begin{aligned} & [C_i(x_i, q_i(x'_i, x_{-i})) + m_i(x'_i, x_{-i})] - [C_i(x_i, q_i(x)) + m_i(x)] \\ &= [C_i(x_i, q_i(x'_i, x_{-i})) - C_i(x'_i, q_i(x'_i, x_{-i}))] + [C_i(x'_i, q_i(x'_i, x_{-i})) + m_i(x'_i, x_{-i})] - [C_i(x_i, q_i(x)) + m_i(x)] \\ &= [C_i(x_i, q_i(x'_i, x_{-i})) - C_i(x'_i, q_i(x'_i, x_{-i}))] + [C_i(x'_i, 0) - C_i(x_i, 0)] - (h_i + p_i) \int_{x'_i}^{x_i} G_i(q_i(z, x_{-i}) - z) dz \end{aligned}$$

$$=(h_i + p_i) \int_{x'_i}^{x_i} [G_i(q_i(x'_i, x_{-i}) - z) - G_i(q_i(z, x_{-i}) - z)] dz \geq 0,$$

where the last inequality is due to the fact that if $x'_i > (<)x_i$, $q_i(x'_i, x_{-i}) \geq (\leq)q_i(z, x_{-i})$ for all $z \in [x_i, x'_i]$ ($z \in [x'_i, x_i]$) because of monotonicity of $q_i(x)$ in x_i for any given x_{-i} . This shows (A3) and taking the expectation of (A3) with respect to x_{-i} yields (IC_i^P). \square

Proof of Lemma 3. Replace the term $C_0(y, q(x))$ and $\{\mathbb{E}_{x_{-i}}[m_i(x)]\}_{i=1}^N$ in (9) with the expression in (7) and (A2), respectively. In light of Lemma 1 and Lemma 2, we can focus on the following relaxed minimization problem:

$$\begin{aligned} \min_{\substack{q_i(\cdot), \dots, q_N(\cdot) \\ W_1(\underline{x}_1), \dots, W_N(\underline{x}_N)}} \mathbb{E}_x \left[\sum_{i=1}^N (c_i - h_0) q_i(x) \right] &+ \sum_{i=1}^N \mathbb{E}_x [C_i(x_i, q_i(x))] \\ &+ \sum_{i=1}^N (h_i + p_i) \mathbb{E}_x \left[\int_{\underline{x}_i}^{x_i} G_i(q_i(z, x_{-i}) - z) dz \right] - \sum_{i=1}^N W_i(\underline{x}_i) \end{aligned} \quad (\text{EC.3})$$

subject to $\sum_{i=1}^N q_i(x) \leq y$, $q_i(x) \geq 0$, and $W_i(\underline{x}_i) \leq C_i(\underline{x}_i, 0)$ for all $x \in \mathcal{X}, i = 1, \dots, N$.

Since the objective function is decreasing in $W_i(\underline{x}_i)$ for $i = 1, \dots, N$, it is optimal to set,

$$W_i^*(\underline{x}_i) = C_i(\underline{x}_i, 0), \quad i = 1, \dots, N.$$

Furthermore, we have,

$$\begin{aligned} \mathbb{E}_x \left[\int_{\underline{x}_i}^{x_i} G_i(q_i(z, x_{-i}) - z) dz \right] &= \mathbb{E}_{x_{-i}} \left[\mathbb{E}_{x_i} \left[\int_{\underline{x}_i}^{x_i} G_i(q_i(z, x_{-i}) - z) dz \right] \right] \\ &= \mathbb{E}_{x_{-i}} \left[\mathbb{E}_{x_i} \left[\frac{1 - F_i(x_i)}{f_i(x_i)} G_i(q_i(x) - x_i) \right] \right] \\ &= \mathbb{E}_x \left[\frac{1 - F_i(x_i)}{f_i(x_i)} G_i(q_i(x) - x_i) \right], \quad i = 1, \dots, N \end{aligned}$$

where the second equality follows from integration by parts. Substituting the last expression into (EC.3) yields (A4). The second part of the result follows from Lemma 2. \square

Proof of Lemma 4. The required monotonicity constraint is satisfied by q^* according to Lemma EC.4. Then the result immediately follows from Lemma 3. \square

Appendix EC.3: Quasi-convexity and Monotonicity of (10)

Lemma EC.1 below will be applied through out the paper with $\alpha = (h_0 + p_i - c_i)/(h_i + p_i)$, $G = G_i$, $\underline{d} = \underline{d}_i$, $\bar{d} = \bar{d}_i$, $g = g_i$, $\zeta = \frac{1 - F_i(x_i)}{f_i(x_i)} \geq 0$ for some i .

LEMMA EC.1. *Let G be a probability distribution supported on $[\underline{d}, \bar{d}]$ with a upper-semi continuous probability density function g such that $1 - G$ is log-concave, $\zeta \geq 0$, and $\alpha \in (0, 1)$. Define $z^* := \inf\{z \in [\underline{d}, \bar{d}] \mid -\alpha + G(z) + \zeta g(z) \geq 0\}$. Then*

- (i) $-\alpha + G(z) + \zeta g(z)$ is nondecreasing for $z \leq z^*$;
(ii) $-\alpha + G(z) + \zeta g(z) \geq 0$, for all $z \geq z^*$.

Proof. It is equivalent to show that $1 - G(z) - \zeta g(z)$ is non-increasing in $z \leq z^*$ and for $z \geq z^*$,

$$1 - G(z) - \zeta g(z) \leq 1 - \alpha. \quad (\text{EC.1})$$

By definition of z^* , if $1 - G(z) - \zeta g(z) \leq 0$, we must have $z \geq z^*$ and (EC.1) holds for this case. Otherwise note that

$$\log(1 - G(z) - \zeta g(z)) = \log(1 - G(z)) + \log\left(1 - \zeta \frac{g(z)}{1 - G(z)}\right).$$

By the monotonicity of G we have $\log(1 - G(z))$ is non-increasing, and by log-concavity of $1 - G$ we have that $-g(z)/[1 - G(z)]$ is non-increasing in z . Therefore both terms are non-increasing in z , establishing (i) and (ii) since $1 - G(z^*) - \zeta g(z^*) \leq 1 - \alpha$. \square

Lemma EC.2 below will typically be applied to $\alpha_i = (h_0 + p_i - c_i)/(h_i + p_i)$, $a = 1$, and $\zeta_i(x_i) = \frac{1 - F_i(x_i)}{f_i(x_i)}$ as a non-increasing function of x_i for fixed x_{-i} .

LEMMA EC.2. *Assume that $\zeta_i(x_i)$ is non-increasing (nondecreasing) in x_i , and let $\alpha_i \in (0, 1)$, $a > 0$, and G_i be a probability distribution with density function g_i . Then $z_i^*(x_i) := \inf\{z \in [\underline{d}, \bar{d}] : -\alpha_i + G_i(z) + a\zeta_i(x_i)g_i(z) \geq 0\}$ is nondecreasing (non-increasing) in x_i .*

Proof. Pick $x_i < x'_i$ so that $\zeta_i(x_i) \leq \zeta_i(x'_i)$. For any z

$$0 \leq -\alpha_i + G_i(z) + a\zeta_i(x_i)g_i(z) \leq -\alpha_i + G_i(z) + a\zeta_i(x'_i)g_i(z)$$

so that any z considered in the infimum problem for $z_i^*(x_i)$ is also considered in the infimum problem for $z_i^*(x'_i)$. Thus, $z_i^*(x_i) \geq z_i^*(x'_i)$. Similar arguments apply when $\zeta_i(x_i)$ is non-increasing in x_i . \square

In what follows we need the definition

$$\mu_i(z|x_i) := (h_i + p_i)\tilde{G}_i(z|x_i) - (h_0 + p_i - c_i), \quad i = 1, \dots, N. \quad (\text{EC.2})$$

LEMMA EC.3. *Under Assumptions 1 and 2, the solution $q^*(\cdot)$ to (10) can be characterized as follows: there is an index $n^* = n^*(x, y)$ and a Lagrange multiplier $L^* = L^*(x, y) \in [c_{n^*} - p_{n^*} - h_0, 0]$ and such that*

1. $\mu_i(q_i^*(x, y) - x_i|x_i) = L^*$ for $i \leq n^*$, for which $q_i^*(x, y) > 0$.
2. $c_j - p_j - h_0 \geq L^*$ for $j > n^*$, for which $q_j^*(x, y) = 0$.
3. $\sum_{i=1}^N q_i^*(x, y) \leq y$ and $L^* \cdot \left(\sum_{i=1}^N q_i^*(x, y) - y\right) = 0$.

Proof. Let

$$V_i(z|x_i) := (c_i - P_i - h_0)z + (h_i + p_i) \left[\int_{\underline{d}_i}^z G_i(u)du + \frac{1 - F_i(x_i)}{f_i(x_i)} G_i(z) \right]. \quad (\text{EC.3})$$

Then, the objective function in problem (10) can be written as $\sum_{i=1}^N V_i(q_i - x_i|x_i)$ plus some constant independent of q . Straightforward computation reveals that $\frac{d}{dz} V_i(z|x_i) = \mu_i(z|x_i)$ defined in (EC.2) and $\frac{d}{dz} V_i(0|x_i) = c_i - p_i - h_0 < 0$ for all i . Therefore, there must be some $q_i^*(x, y) > 0$. In addition, Lemma EC.1 establishes that $V_i(\cdot|x_i)$ is quasi-convex over the whole line, reaches its minimum at $z_i^*(x_i) := \inf\{z \in [\underline{d}, \bar{d}] : -\frac{h_0+p_i-c_i}{h_i+p_i} + G_i(z) + \frac{1-F_i(x_i)}{f_i(x_i)} g_i(z) \geq 0\}$ and is convex over $[-\infty, z_i^*(x_i)]$. Thus, KKT conditions are necessary and sufficient to characterize the solution. Let $L^* = L^*(x, y)$ be the Lagrange multiplier for the capacity constraint $\sum_{i=1}^N q_i \leq y$. Thus we have $\mu_i(q_i^*(x, y) - x_i|x_i) = L^*$ for those i such that $q_i^*(x, y) > 0$ and $c_j - p_j - h_0 \geq L^*$ for those j such that $q_j^*(x, y) = 0$.

Let i be such that $q_i^*(x, y) > 0$. Then, $L^* = \mu_i(q_i^*(x, y) - x_i|x_i) \geq c_i - p_i - h_0$ and $L^* = \mu_i(q_i^*(x, y) - x_i|x_i) \leq 0$ because $q_i^*(x, y) - x_i \leq z_i^*(x_i)$, over which $\mu_i(\cdot|x_i) \leq 0$ by quasi-convexity (Lemma EC.1). The complementarity condition follows from the fact that if $\sum_{i=1}^N q_i^*(x, y) < y$, then we must have $q_i^*(x, y) - x_i \geq z_i^*(x_i)$ and $L^* = \mu_i(z_i^*(x_i)|x_i) = 0$ by definition. Finally, since $c_i - p_i - h_0$ is in an ascending order, we just need to let $n^* = \max\{i \geq 0 : q_i^*(x, y) > 0\}$. \square

LEMMA EC.4. *Under Assumptions 1 and 2, there exists a solution q^* to (10) such that, for $i = 1, \dots, N$, $q_i^*(x, y)$ is nondecreasing in x_i and non-increasing in x_j for any $j \neq i$.*

Proof. For fixed x_{-i} and $x_i > x'_i$, consider $q = q^*((x_i, x_{-i}), y)$ and $q' = q^*((x'_i, x_{-i}), y)$. We can assume $q'_i > 0$; otherwise we are done.

We first claim that we can assume $q_i > 0$. Suppose the opposite, then we must have $i > 1$ because $q'_1 > 0$ and $q_1 > 0$ for sure. Now, $q_i = 0$ implies that $q_j = 0$ for all $j \geq i$. Therefore, we must have $q_k > q'_k > 0$ for some $k < i$. By Lemma EC.3 and the monotonicity of $\mu_k(\cdot|x_k)$ in the relevant region,

$$c_i - p_i - k \leq \mu_i(q'_i - x'_i|x'_i) = \mu_k(q'_k - x_k|x_k) \leq \mu_k(q_k - x_k|x_k) = L,$$

where L is the Lagrange multiplier characterized in Lemma EC.3. Again, by Lemma EC.3, $q_i = 0$ also implies $c_i - p_i - k \geq L$. Thus, the only possibility is that $L = c_i - p_i - h_0 = c_j - p_j - h_0$ for all $j \leq i$, under which situation it is obvious how to construct an optimal solution satisfying the monotonicity conditions in the lemma. Therefore, let us assume $q_i > 0$.

By Lemma EC.3, q and q' are characterized by the existence of multipliers L and L' , and integers n and n' such that

$$\begin{aligned} j \leq n, j \neq i, \mu_j(q_j - x_j|x_j) = L, q_j > 0 & \quad j \leq n', j \neq i, \mu_j(q'_j - x_j|x_j) = L', q'_j > 0 \\ \mu_i(q_i - x_i|x_i) = L & \quad \mu_i(q'_i - x'_i|x'_i) = L' \\ j > n, j \neq i, c_j - p_j - h_0 \geq L, q_j = 0 & \quad j > n', j \neq i, c_j - p_j - h_0 \geq L', q'_j = 0 \\ L \cdot \left(\sum_{j=1}^N q_j - y \right) = 0 & \quad L' \cdot \left(\sum_{j=1}^N q'_j - y \right) = 0. \end{aligned}$$

Since $\mu_i(z|x_i) \leq \mu_i(z|x'_i)$ for all z under Assumptions 1 and 2, it follows that $0 \geq L' \geq L$. Moreover, note that $q_j - x_j \leq z_j^*(x_j)$ if $j \leq n$ and $q'_j - x_j \leq z_j^*(x_j)$ if $j \leq n'$. Therefore, since $\mu_j(\cdot|x_j)$ is nondecreasing for $z \leq z_j^*(x_j)$ by Lemma EC.1 (i), it follows that $q'_j \geq q_j$ for $j \leq \max\{n, n'\}$, $j \neq i$.

Thus, note that if $L < 0$ the conditions above imply $\sum_{i=1}^N q_i = y$ and we have

$$q'_i \leq y - \sum_{j \neq i} q'_j \leq y - \sum_{j \neq i} q_j = q_i$$

and the result follows. On the other hand, if $L = 0$, we also have $L' = 0$ and $q'_i = \max\{0, z_i^*(x'_i) + x'_i\} \leq \max\{0, z_i^*(x_i) + x_i\} = q_i$ since $z_i^*(x_i) + x_i$ is nondecreasing in x_i by Lemma EC.2. \square

Appendix EC.4: Data Source for Calibrated Numerical Study in Section 5.1

This appendix contains Table EC.1 and Figure EC.1.

Table EC.1 Calibration of the principal's cost parameter h_0 .

Company	Sanofi Pasteur	Novartis	GSK
Facility Location	Swiftwater, PA, USA ^b	Holly Springs, NC, USA ^c	Dresden, Germany ^e
Capacity (mil. doses)	100	150	35 ^f
Facility Value (\$ mil.) ^a	150	1,000	160
2013 Asset Value of Property, Plant & Equipment (\$ mil.)	13,004	18,197	13341
2013 Annual Selling & General Expense (\$ mil.)	10,986	17,609	12752
Unit Cost of Unused Capacity (\$/Unit Capacity) ^b	1.27	6.45 ^d	3.98

^a All the currency is converted to U.S. dollars using average exchange rates of year 2013 published by IRS (<http://www.irs.gov/Individuals/International-Taxpayers/Yearly-Average-Currency-Exchange-Rates>, accessed on July 5, 2015).

^b Unit Cost of Unused Capacity = $\frac{\text{Facility Value}}{\text{Value of Property, Plan \& Equipment}} \times \frac{\text{Annual Selling \& General Expense}}{\text{Capacity}}$.

^c The facility information is extracted from Sanofi Pasteur's press release (http://en.sanofi.com/Images/13949_20090525_h1n1_en.pdf, accessed on July 5, 2015).

^d The facility information is extracted from news report on <http://www.cidrap.umn.edu/news-perspective/2014/10/csl-novartis-deal-includes-us-cell-based-flu-vaccine-plant>, accessed on July 5, 2015.

^e Novartis reported an operating loss in 2013 for their vaccines segment.

^f The facility information is extracted from news report on <http://www.pharmaceutical-technology.com/projects/gsk-biologicals/>, accessed on July 5, 2015.

^g The €125 million investment expanded the Dresden plant's plant capacity from 35 to 70 million doses.

Vaccine	Brandname/ Tradename	NDC	Packaging	CDC Cost/ Dose	Private Sector Cost/ Dose	Contract End Date	Manufacturer	Contract Number
Influenza [5, 6] (Age 6 months and older)	Fluzone®	49281- 0392-15	10 dose vial	\$8.153	\$10.69	2/21/2014	Sanofi Pasteur	200-2013- 54009
Influenza [5] (Age 18 - 64 years)	Fluzone®	49281- 0707-55	10 pack - 1 dose syringe	\$12.644	\$16.72	2/21/2014	Sanofi Pasteur	200-2013- 54009
Influenza [5] (Age 36 months and older)	Fluzone® No Preservative	49281- 0013-50	10 pack - 1 dose syringe	\$9.494	\$12.49	2/21/2014	Sanofi Pasteur	200-2013- 54009
		49281- 0013-10	10 pack - 1 dose vial	\$9.93	\$13.075			
Influenza [5] (Age 18 years and older)	Flucelvax® Preservative Free Antibiotic free	63851- 0612-01	10 pack - 1 dose syringe	\$9.50	\$18.25	2/21/2014	Novartis	200-2013- 54011
Influenza [5, 6] (Age 4 years and older)	Fluvirin®	66521- 0116-10	10 dose vial	\$6.75	\$13.25	2/21/2014	Novartis	200-2013- 54011
Influenza [5] (Age 4 years and older)	Fluvirin® Preservative Free	66521- 0116-02	10 pack - 1 dose syringe	\$7.75	\$14.35	2/21/2014	Novartis	200-2013- 54011
Influenza [5, 6] (Age 18 years and older)	FluLaval®	19515- 0890-07	10 dose vial	\$5.89	\$9.50	2/21/2014	GlaxoSmithKline	200-2013- 54008
Influenza [5] (Age 36 months and older)	Fluarix® Preservative Free	58160- 0880-52	10 pack - 1 dose syringe	\$8.08	\$10.98	2/21/2014	GlaxoSmithKline	200-2013- 54008
	Fluarix® Quadrivalent Preservative Free	58160- 0900-52	10 pack - 1 dose syringe	12.03	15.90	2/21/2014	GlaxoSmithKline	200-2013- 54008
Influenza [5] (Age 9 years and older)	Afluria® No Preservative	33332- 0013-01	10 pack-1 dose syringe	\$8.13	\$11.00	2/21/2014	Merck (CSL product)	200-2013- 54010
Influenza [5, 6] (Age 9 years and older)	Afluria®	33332- 0113-10	10 dose vials-1 pack	\$7.819	\$10.25	2/21/2014	Merck (CSL product)	200-2013- 54010

Figure EC.1 Archived CDC Price List for Adult Influenza Vaccine as of September 30, 2013 (screenshot).

References

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